

## **Description**

PX4Flow is an optical flow smart camera. It has a native resolution of 752×480 pixels and calculates optical flow on a 4x binned and cropped area at 250 Hz (bright, outdoors), giving it a very high light sensitivy.

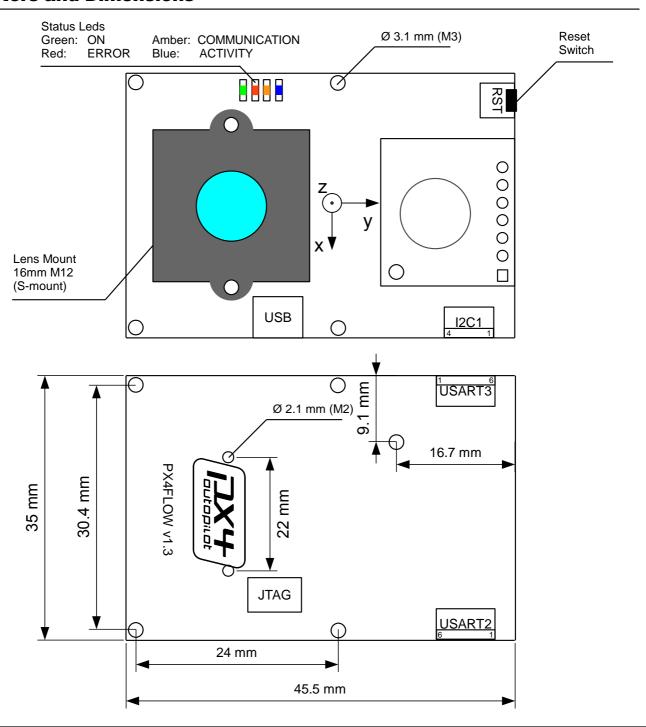
Unlike many mouse sensors, it also works indoors and in low outdoor light conditions without the need for an illumination LED at 120 Hz (dark, indoors). It can be freely reprogrammed to do any other basic, efficient low-level computer vision task.

#### **Features**

- •168 MHz Cortex M4F CPU (128 + 64 KB RAM)
- •752x480 MT9V034 image sensor
- •L3GD20 3D Gyro
- •16mm M12 lens (IR block filter)
- •Size 45.5 mm X 35 mm
- •Power consumption 115mA / 5V

http://pixhawk.ethz.ch/px4/

### **Connectors and Dimensions**



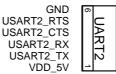
## **Pinout and absolute maximum Ratings**

 Input: 4.3-6 V (VDD\_5V), 115mA onboard use, max. 800 mA for peripherial load

• Output: 3.3 V (VDD\_3V3), 500 mA



Mates 4 pos Hirose DF13 housings Part # DF13-4S-1.25C Crimp terminals Part # DF13-2630SCF (for AWG 26-30 wire)



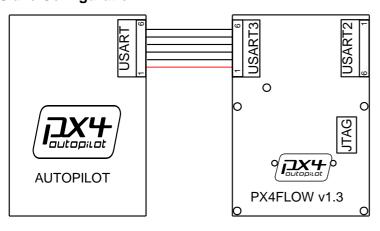
Mates 6 pos Hirose DF13 housings Part # DF13-65-1.25C Crimp terminals Part # DF13-2630SCF (for AWG 26-30 wire) GND
USART3\_CTS
USART3\_RTS
USART3\_TX
USART3\_RX
VDD\_5V

UART3

Mates 6 pos Hirose DF13 housings Part # DF13-6S-1.25C Crimp terminals Part # DF13-2630SCF (for AWG 26-30 wire)

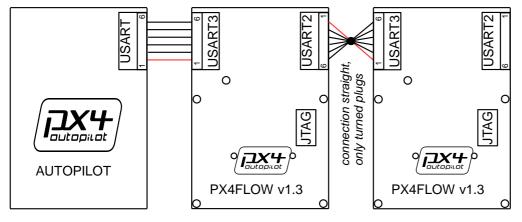
## **Assembly Instructions**

### Slave Configuration



 PX4FLOW acts as a slave and is connected to a host device e.g. autopilot board using the USART3 port.

### Daisy Chain Configuration



PX4FLOW modules can be connected in series to attach several modules on a single USART port of a host device

# **Open Hardware License**

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