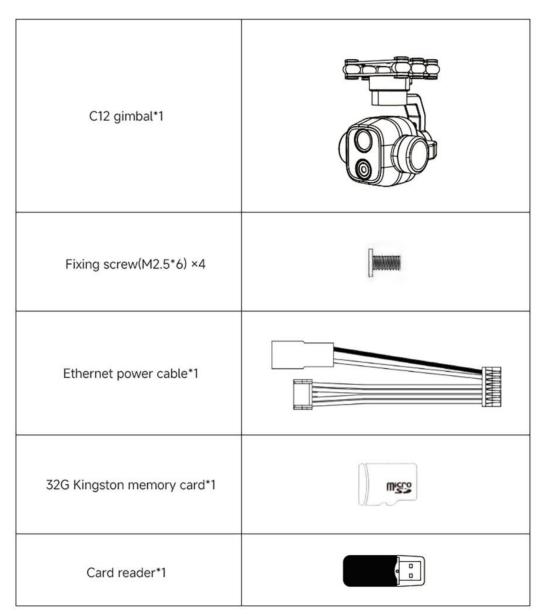
# Skydroid C12 User Manual

#### **Product introduction:**

C12 is a small high-definition dual light gimbal that uses a new generation imaging chip and a highdefinition distortion free camera, with effective pixels reaching 5 million. It has powerful 2K video recording and photography capabilities, supports digital zoom, and captures clear images anytime, anywhere, making distant scenery closer to you. Equipped with a high-resolution thermal imaging camera, it has a wide field

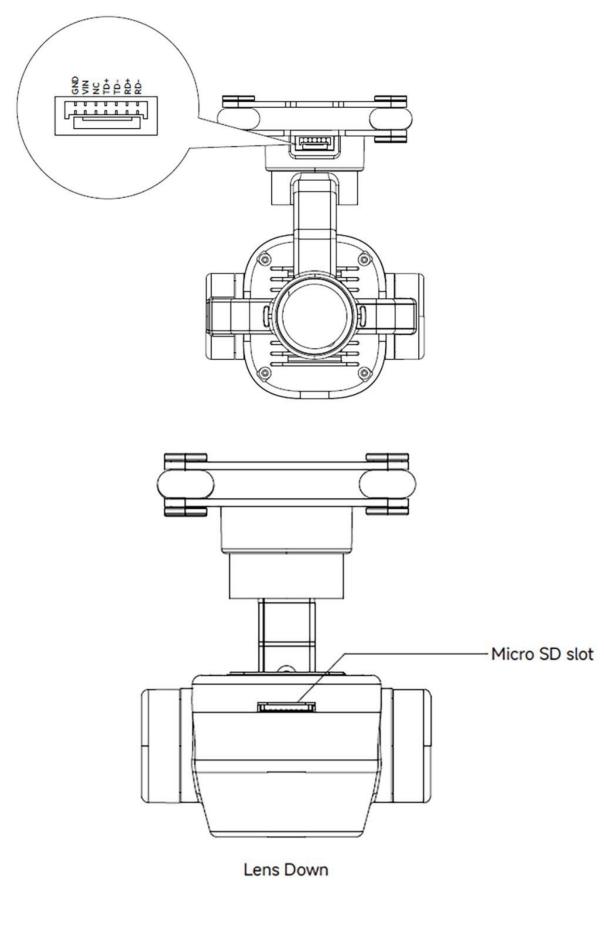
of view, clear images, and can observe various heat sources from a long distance. Using an industrial grade 3-axis stabilization structure, it significantly reduces image jitter and keeps the image in a stable state. Can be used in fields such as fire rescue, animal protection, and safety monitoring.

**Product packing List** 



## Overview of C12

C12 ports introduction



Product specifications

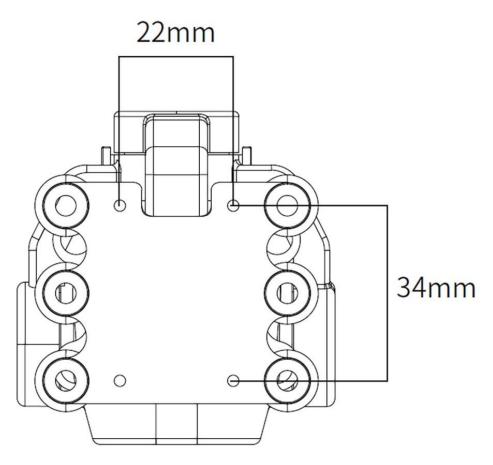
C12 gimbal parameters	
Video output signal interface	LAN port
Control signal input interface	LAN port
Working voltage	7.2V~72V
Working current	210mA
Working temperature	-10°C~+50°C
Weight ( includes quick disassemble shock absorber plate )	117g
Size ( includes quick disassemble shock absorber plate )	62mm(L)*65mm(W)*86mm(H)
Controllable angle range	-90°~+10° (Pitch);-90°~+90°(Direction);-45°~+45° (Roll)
Hoist mode/ Upside down mode	support
One click back/One click down/One click head up	support

C12 visible light camera parameters		
Lens resolution	500万	
Focal length	f=3.5~4.75mm	
Aperture	F2.0	
HFOV / VFOV / DFOV	100° / 52° / 122°	
Zoom magnification	4x Electron magnification	
Image transmission resolution	1280*720	
Video record resolution	2560*1440	
Video storage format	MP4	
Photography resolution	2560*1440	
Photo storage format	JEPG	
Supports storage card types	Supports Micro SD storage (up to 256GB)	
Support file system	FAT32	
C12 thermal imaging camera parameters		
Resolution	384*288	

Frame rate	≤25Hz
Thermal time constant	<10ms
Focal length	7mm
Aperture	F1.0
FOV	24.8°*18.7°
Pixel spacing	12µm
Spectral range	8~14µm

Installation and debugging

The schematic diagram of the screw hole position and spacing is as follows:



Note: The screw size used to fix the shock absorber plate is M3 \* 8, with a quantity of 4 pieces.

When the gimbal is not in use, do not hang it on the drone. Long time suspension will accelerate the deformation of the shock-absorbing ball, leading to a decrease in shock-absorbing effect and jelly phenomenon.

When installing the gimbal, the shock absorption plates shall be kept absolutely perpendicular and parallel to each other. Incorrect installation will cause deformation of the shock absorption ball, resulting in a decrease in shock absorption effect and inability to self check.

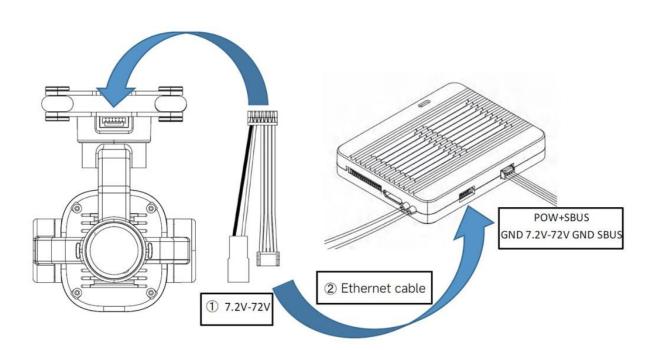
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Gimbal working mode

The hoist mode or upside down mode can be set on the FPV App

Note: The default hoist mode is set before shipping, please do not invert and power on; Please place the gimbal correctly according to the working mode. Incorrect placement may cause damage to the gimbal motor.

Gimbal cable connection diagram and explanation



①Power supply	Red JST-2P male port,Power supply: 7.2V-72V (DC power supply or lithium battery)		
②Ethernet cable (signal transmission)	Network IP signal	RX-: Network IP signal RX+: Network IP signal TX-: Network IP signal TX+: Network IP signal	
Video transmission	Visible light video output RTSP stream rtsp://192.168.144.108:554/stream=1		
	Thermal imaging video output RTSP stream rtsp://192.168.144.108:555/stream=2		

### Use of C12

Install the latest version of gimbal FPV software on the remote control and open it. Software download address: http://file.skydroid.xin/SkydroidCameraFPV.apk

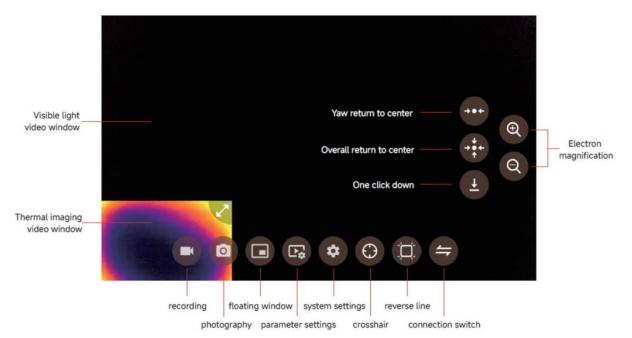
### 1 Power on it

After the installation of the gimbal is fixed, power on it. Please wait for power on to complete.

(2) Open the gimbal FPV, select the C12 connection, and click to enter.



# 3 Introduction to the homepage of gimbal FPV



## ④FLY GCS settings

APP homepage top left corner  $\rightarrow$  Common settings  $\rightarrow$  Other settings  $\rightarrow$  User interface  $\rightarrow$  Video window  $\rightarrow$  C12

Note: C12 is a dual beam gimbal that requires both video windows to be set

Widgets			
Widgets Preferen	ces	Video List	
Video Preferences	Left Video:	Topotek Double	
		Topotek Three	
Maps Maps Providers	Right Video	C10/C10Pro/Single axis gimb	al
baidu map		C12 VL	
Map Provider Pre Configure the select		C12 IR	
Disnlay no fly zon	es	C20	

Parameter settings for C12

图像参数	
Pan tilt control	
PTZ calibration	+•+ ( <del>)</del>
Operating mode	÷÷÷ ₽
Speed	± 9
Palette	
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Image parameters

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Brightness	Ð
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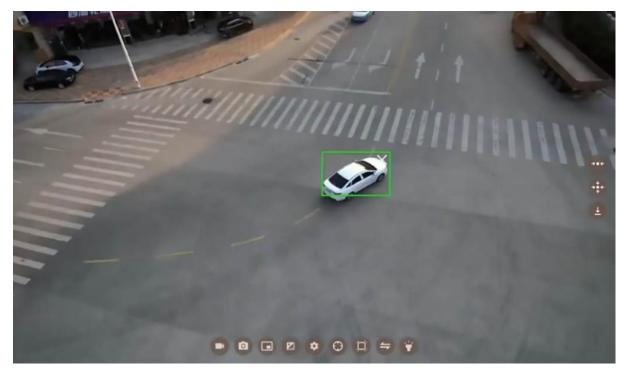
You can set some relevant camera parameters

Gimbal control.

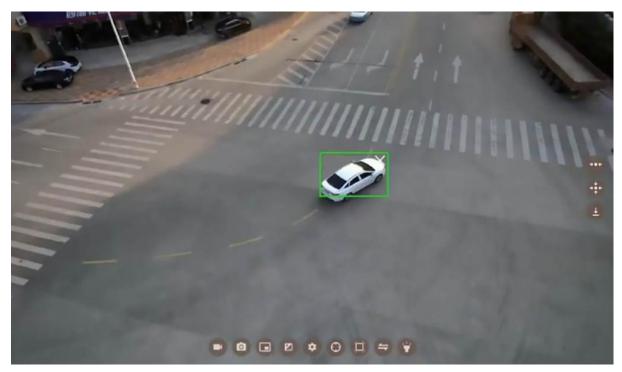
Click on parameter settings  $\rightarrow$  gimbal control, there are target tracking and other three control ways to choose, which can be chosen simultaneously. (Target tracking can be used simultaneously with gesture control).

	云台控制	
	目标跟随	
	使用虚拟摇杆	Ð
	使用手势	Q
	使用遥控器	
	遥控器通道自定义	
E	确认	

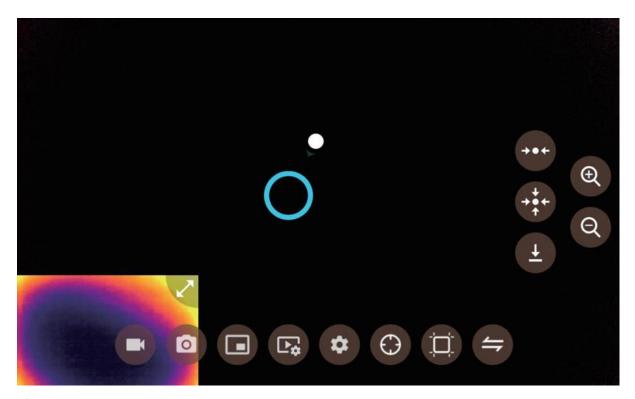
1C12's' target tracking, after selecting this function, C12 will automatically track the target



2 Virtual joystick control, which can control C12 tilt through it, and supports one click return to center function.



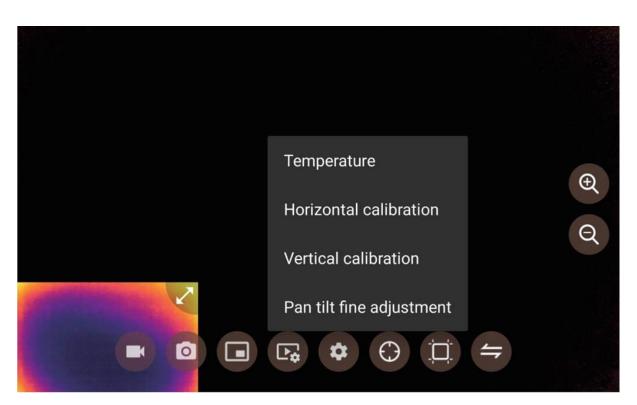
③ Gesture control, controlling C12 tilt by sliding the screen.



(4) Use remote control channel to control it, using custom remote control channels to control C12, as well as functions such as photography and video recording. (The remote control channel can be viewed and queried through the Remote Control Assistant  $\rightarrow$ Rudder View)

Customizing Rer	note Control Buttons	
Butto	n Action	
Enall <sup>i</sup> chan1	1 Gimbal yaw	<b>→•</b> + <b>(</b>
chan1	2 Gimbal pitch	*** ***
chan		L Q
Enable Ren	<mark>-</mark> Up	Ě.
Tips:Long Press	s to Delete Center	
CANCEL		
	Down	

Gimbal calibration

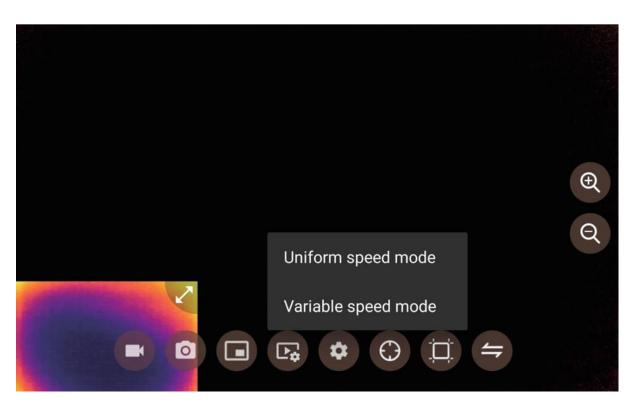


Temperature calibration: Calibrate the temperature of the C20 during use to avoid the inability of C20 due to significant differences between the ambient temperature and the operating temperature of the IMU. Horizontal calibration: Please place the gimbal on a horizontal plane and ensure that it is in a stationary state, and do not touch or shake the gimbal.

Vertical calibration: After the horizontal calibration is completed, the gimbal will automatically pitch downwards, ensuring that the gimbal is in a stationary state and not touching or shaking the gimbal. And then, do calibration is OK.

C20 fine adjustment: Fine adjust the horizontal and pitch axes of the gimbal.

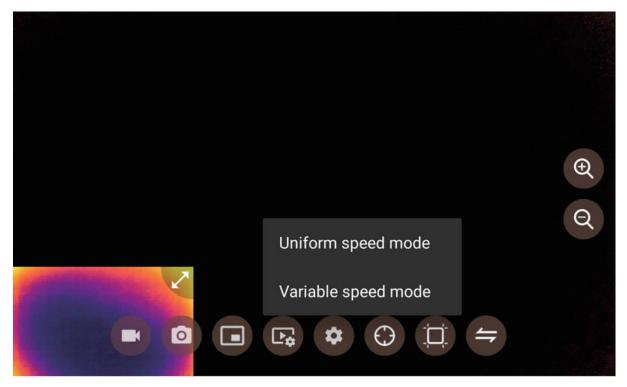
Gimbal working mode



Can set the C12 Pro in hoist mode or upside down mode

Note:Please place the gimbal correctly according to the working mode. Incorrect placement may cause damage to the gimbal motor.

Gimbal speed



The control speed of the gimbal includes constant speed mode and variable speed mode.

Color palette

White Hot	
Sepia	
Ironbow	
Rainbow	Ð
Night	Q
Aurora	
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There are eleven optional imaging effects for adjustable thermal imaging cameras.

Setting Encoding Mode

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Open hardware decoc		
RTSP streams use TC	er	-
Set IP		-192.168. <b>144.108 &gt;</b>
	-gop 30	
Encoding mode	Bit rate 2048	>
firmware upgrade		- >

You can set the screen to flip, view the camera firmware version, and display OSD.

Firmware Upgrade

Upgradeable the C12 firmware and camera firmware. Please do not power off or exit the upgrade interface during the upgrade process. (When upgrading camera firmware, C12 shall with a TF card inserted)

C12 size, angle annotation

Due to version evolution and changes in customer requirements, corresponding commands and controls may change. Please contact Skydroid Co., Ltd. for the latest information and technical support. Due to product updates and upgrades, parameters such as size and weight may change. We apologize for any inconvenience caused by this.

#### Precautions

To prevent you and others from harm or damage or protect your device, please read all the following information

before using your device.

- 1. Do not put the components directly at high-intensity radiation sources such as the sun;
- 2. The ideal operating environment temperature is -40 °C~80 °C;
- 3. Do not touch the device and cables with wet hands;
- 4. Do not bend or damage the connecting cables;
- 5. Do not use diluents to scrub your equipment;
- 6. Do not plug or unplug cables without disconnecting the power supply;
- 7. Do not connect the attached cables incorrectly to avoid damaging the equipment;
- 8. Please pay attention to preventing static electricity;
- 9. Please do not disassemble the equipment. If there is a malfunction, please contact our company for professional repair.