









L	12	
F	6	

注: A-H为重点管控尺寸

P. C. B. MOUNTING DETAIL

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				品 名	EC11A 5	EA20P	1SK12F6	3
				图号	EC	11A-02	9	
	修改	记录		绘制人	未标注尺寸公	差	比例	3:1
	初始发				L≤10	±0.3	单 位	mm
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					ANGLE	±5°		
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EC11 FORWARD DIRECTION SERIES SPECIFICATION

1. 一般事项General

1-1. 适用规格 Scope

本规格书适用于微小电流回路的电子设备,属11型回转型编码器.

This specification applies to 11mm size low-profile rotary encoder(incremental type)

for microscopic current circuits, used in electronic equipment.

1-2. 标准状态Standard atmospheric conditions

除另有规定外,测量应在以下状态下进行:

Unless otherwise specified, the standard range of atmospheric conditions for making measurements and test is as following limits:

温 度 Ambient temperature : 15℃ to 35℃ 相对湿度 Relative humidity : 25% to 85% 气 压 Air pressure :86kpa to 106kpa

如果对在上述所提到的条件中所做的实测值有疑问的话,应使用以下条件进行测量:

If doubt arises on the decision based on the measured values under the above-mentioned conditions, the following conditions shall be employed:

温 度 Ambient temperature : 20±1℃ 相对湿度 Relative humidity : 63% to 67%

气 压 Air pressure :86kpa to 106kpa

1-3. 使用温度范围

Operating temperature range :-30℃ to+80℃

1-4. 保存温度范围

Storage temperature range : -40°C to+85°C

2. 构造Construction

2-1. 尺寸 Dimensions

见所附成品图 Refer to attached drawing

3. 额定值 Rating

3-1. 额定电压

Rated voltage:DC 5V

3-2. 最大额定电流(阻抗负载)

Maximum operating current (resistive load) 各相导线 Each lead: 0.5mA(Max 5mA;Min 0.5mA) 公共导线Common lead:1mA(Max 10mA;Min 0.5mA)

10KΩ Terminal A A 端 子 Aο 10KΩ Encoder 10KΩ 0.01μF Terminal C C 端 子

图1 fig. 1

4. 使用上的事项Application Notes

4-1. 避免储藏于高温潮湿及腐蚀的场所. 产品购入后尽可能在6个月内使用完. 拆包装后未使用完的剩余产品需储藏于防潮防毒的环境下.

Avoid storing the products in a place at high temperature, high humidity and in Corrosive gases. Please use this product as soon as possible with 6 months limitation. If any remainder left after packing is opened, please store it with proper moisture proofing, gasproofing etc.

4-2. 编码器信号的计算方法应将操作的速度,信号的取样时间及电子回路中的微电脑软体等考虑进去.

The encoder pulses count method should be designed with taking operating speed, sampling time and esign of the microcomputer software into cosideration.

4-3. 此产品在定位点的输出波形参照(5-1),因此在设计软体时请留意其状态,推荐以A相位为参考基准。 With this products the detent position output consult fig.5-1. Therefore make the A phase the reference at the soft ware design stage. Recommended that use A output signal for the reference.

4-4. 在设计时要考虑到杂讯, 建议使用R/C滤波电路, (图1)

At design of the pulse count process. Using the C/R filter circuit is Recommended. (fig. 1)

4-5. 本产品请勿碰触到水, 可能会导致输出波形的异常.

Care must be taken not to expose this product to water or dew to prevent possible problem in pluses output waveform.

EC11 FORWARD DIRECTION SERIES SPECIFICATION

5. 电气性能 Elect			SERIES SPECIFICATIO			
项目	条件			规格		
ITEM		CONDITIONS	SPECIFICATIONS			
	A、B两信号输出相位差,输出波形详细见(图2/3)(虚线表示带卡点装置的上擎子处位置)					
	2 Phase-different signals (signal A, signal B) Details shown in fig. 2/3> (The broken line shows detent position.)					
	轴回转方向	信号		输出波形		
	Shaft rotati-	Signal		Output		
5-1. 输出信号	onal direction		图3 fig.3			
Output signal		A(A-C端子间)	OFF —			
format	顺时针方向	A(TerminalA-C)	ON	ON L		
	C. W	B(B-C端子间)	OFF ON	OFF ON		
		B(TerminalB-C)	OFF ! !	OFF !		
		A(A-C端子间)	ON	ON		
	逆时针方向	A(TerminalA-C)	OFF 7	- OFF		
	C. C. W	B(B-C端子间)	ON — I — I	ON		
		B(TerminalB-C)				
				□15 个脉冲/360°(图2)		
5-2. 分解能力	回转360°的输出脉	仲数.	15pulses/360° (fig.2)			
Resolution	Number of pulses	in 360° rotation.		■20个脉冲/360° (图3)		
				20pulses/360° (fig.3)		
	下(图4)所示回路,轴以360°/S的速度转动测定。					
	Measurement shall be made under the condition as follows.					
	Shaft rotational speed : 360° /S					
5-3. 开关特性						
Switching						
characteristics						
	777777, C 端 子					
	(注)编码OFF指输出电压3.5V以上的状态(fig.5).					
	Code-OFF area :The area which the voltage is 3.5V or more(fig.5). 编码ON指输出电压1.5V以下的状态(fig.5). Code-ON area : The area which the voltage is 1.5V or less(fig.5).					
	编码从OFF→ON或ON					
5-3-1. 振荡	间. 应符合规定Spec		t1,t3 ≤3mS			
Chattering	time from 1.5V to					
	position(code OFF					
	编码ON部份的1.5V以					
	间会产生1mS以上,1.					
5-3-2. 滑动杂讯	1.5V以下的范围在1mS以上时,则判定为另一个突跳.					
(突跳)Sliding	Specified by the time of voltage change exceed					
noise (Bounce)	1.5V in code-ON area . When the bounce has code $$t2\!\!\leqslant\!\!2mS$$			t2≤2mS		
	-ON time less than 1mS between chattering (tlor t3)the voltage change shall be regarded as a part of chattering. When the code-ONtime between 2 bounces is					
	less than 1mS. they are regarded as 1 linked bounce.					

EC11正向系列规格书

EC11 FORWARD DIRECTION SERIES SPECIFICATION 5-3-3. 滑动噪音 Sliding noise The voltage change in code-OFF area. To (图6) 所示回路,轴以360°/S的速度转动测定。 Measurement shall be made under the condition which the shaft is rotated at 60r/min 5-4. 相位差 Phase difference difference 5-5. 绝缘阻抗 Insulation resistance which a voltage of 250V DC is applied between individual terminals and frame. 5-6. 耐电压 Dielectric strength Iniute between individual terminals and frame. 5-7. 端子间接触阻抗 Contact resistance which a voltage of 300V AC shall be applied for strength I minute between individual terminals and frame. 5-7. 端子间接触阻抗 Contact resistance which a voltage of 300V AC shall be applied for strength I minute between individual terminals and frame. 5-7. 端子间接触阻抗 Contact resistance which a voltage of 300V AC shall be applied for strength I minute between individual terminals and frame. 5-7. 端子间接触阻抗 Contact resistance which a voltage of 300V AC shall be applied for a without arcing or breakdown. 1 □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □
Sliding noise The voltage change in code-OFF area. T (图6) 所示回路,轴以360°/S的速度转动测定。 Measurement shall be made under the condition which the shaft is rotated at 60r/min 5-4. 相位差 Phase difference Signal A Beleg(A~C间) TITITITI Signal B C.W Direction 5-5. 绝缘阻抗 Tri、T2、T3、T4≥0.08T 见图6 (fig. 6) Employed Beleg(B~C间) TITITITI Signal B C.W Direction 5-5. 绝缘阻抗 Tri、T2、T3、T4≥0.08T 见图6 (fig. 6) Employed Beleg(B~C间) TITITITI Signal B C.W Direction 5-6. 砂电压 which a voltage of 250V DC is applied between individual terminals and frame. 5-6. 砂电压 在端子和支架间施加AC300V电压1分钟 Dielectric A voltage of 300V AC shall be applied for Strength I minute between individual terminals and frame. 5-7. 端子间接触阻抗 Contact resistance Measurement shall be stable condition which a output signal is 0N.
下(图6)所示回路,轴以360°/S的速度转动测定。 Measurement shall be made under the condition which the shaft is rotated at 60r/min 5-4. 相位差 Phase difference signal A A信号(A~C间) B信号(B~C间) TIPIPIT Signal B C.W Direction 5-5. 绝缘阻抗 Insulation Measurement shall be made under the condition resistance which a voltage of 250V DC is applied between individual terminals and frame. 5-6. 耐电压 Dielectric A voltage of 300V AC shall be applied for strength 1 minute between individual terminals and frame. 5-7. 端子间接触阻抗 Contact resistance Measurement shall be stable condition which a output signal is 0N.
Measurement shall be made under the condition which the shaft is rotated at 60r/min 5-4. 相位差 Phase difference signal A Bef (A~C间)
which the shaft is rotated at 60r/min That The signal A The signal A The signal B C. W Direction 5-5. 绝缘阻抗 在端子和支架间施加电压 250V DC。 Insulation resistance which a voltage of 250V DC is applied between individual terminals and frame. 5-6. 耐电压 在端子和支架间施加AC300V电压1分钟 The signal B C. W Direction 5-7. 端子间接触阻抗 Contact resistance which a voltage of 300V AC shall be applied for strength 输出信号处于ON时安定状态条件下测定. 6-7. 端子间接触阻抗 Contact resistance which a soutput signal is ON.
To To The Phase difference signal A
Phase difference signal A
Signal A Signal A Signal A Signal A Signal B Signal
B信号(B~C间) TITATA Signal B C.W Direction 5-5.绝缘阻抗 在端子和支架间施加电压 250V DC。 Insulation Measurement shall be made under the condition resistance which a voltage of 250V DC is applied between individual terminals and frame. 5-6.耐电压 在端子和支架间施加AC300V电压1分钟 不得有绝缘破坏 Without arcing or breakdown. 5-7.端子间接触阻抗 输出信号处于ON时安定状态条件下测定. 1Ω以下 Measurement shall be stable condition which a output signal is ON.
B信号(B~C间)
signal B C.W Direction 5-5. 绝缘阻抗 在端子和支架间施加电压 250V DC。 Insulation
5-5. 绝缘阻抗 Insulation resistance which a voltage of 250V DC is applied between individual terminals and frame. 5-6. 耐电压 Dielectric strength I minute between individual terminals and frame. 5-7. 端子间接触阻抗 Contact resistance 6-5. 绝缘阻抗 在端子和支架间施加电压 250V DC is applied between individual terminals and frame. 7-7. 端子间接触阻抗 Contact resistance 6-7. 端子间接触阻抗 Contact resistance 7-8. 他easurement shall be stable condition which a output signal is 0N.
Insulation resistance which a voltage of 250V DC is applied between individual terminals and frame. 5-6. 耐电压 在端子和支架间施加AC300V电压1分钟 不得有绝缘破坏 Without arcing or breakdown. 5-7. 端子间接触阻抗 行动 计算量
Insulation resistance which a voltage of 250V DC is applied between individual terminals and frame. 5-6. 耐电压 在端子和支架间施加AC300V电压1分钟 不得有绝缘破坏 Without arcing or breakdown. 5-7. 端子间接触阻抗 给出信号处于ON时安定状态条件下测定. Contact resistance Measurement shall be made under the condition 100MΩ 以上 100MΩ Min 不得有绝缘破坏 Without arcing or breakdown. 1 minute between individual terminals and frame. 5-7. 端子间接触阻抗 给出信号处于ON时安定状态条件下测定. Measurement shall be stable condition which a output signal is ON.
resistance which a voltage of 250V DC is applied between individual terminals and frame. 5-6. 耐电压 在端子和支架间施加AC300V电压1分钟 不得有绝缘破坏 Without arcing or breakdown. strength 1 minute between individual terminals and frame. 5-7. 端子间接触阻抗 合品
individual terminals and frame. 5-6. 耐电压 在端子和支架间施加AC300V电压1分钟 A voltage of 300V AC shall be applied for strength 1 minute between individual terminals and frame. 5-7. 端子间接触阻抗 Contact resistance Measurement shall be stable condition which a output signal is 0N.
5-6. 耐电压 Dielectric A voltage of 300V AC shall be applied for strength 5-7. 端子间接触阻抗 Contact resistance Taking a policy of 300V AC shall be applied for strength and frame. 5-7. 端子间接触阻抗 物出信号处于ON时安定状态条件下测定. Contact resistance Measurement shall be stable condition which a output signal is ON. Taking a policy of 300V AC shall be applied for without arcing or breakdown. Taking a policy of 300V AC shall be applied for without arcing or breakdown. Taking a policy of 300V AC shall be applied for without arcing or breakdown.
Dielectric strength 1 minute between individual terminals and frame. 5-7.端子间接触阻抗 Contact resistance Mithout arcing or breakdown. 1 minute between individual terminals and frame. 1 □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □
strength1 minute between individual terminals and frame.5-7.端子间接触阻抗 Contact resistance输出信号处于ON时安定状态条件下测定.1Ω以下Measurement shall be stable condition which a output signal is ON.1Ω Max
5-7. 端子间接触阻抗 输出信号处于ON时安定状态条件下测定. 1Ω以下 Contact resistance Measurement shall be stable condition which a output signal is ON.
Contact resistance Measurement shall be stable condition which a output signal is ON. $$1\Omega{\rm Max}$$
output signal is ON.
0. 1/1/1/1/12 E HE MECHANICAL CHAIACTELISTICS
6-1. 全回转角度 360° (无止档点) 260° (死止档点)
Total ratational angle 360° (Endless)
6-2. 定位点力矩 只适用于附卡点装置 2~15mN. m. (20~150gf. cm)
Detent torque Only suitable for C. C, equipment.
6-3. 定位点数及位置 只适用于附卡点装置
Number Only suitable for C. C, equipment.
and position ■20点定位间隔角度18°±2°
of detent 20detents Step angle:18° ±2°
6-4. 轴的推拉强度 在轴端, 沿轴向施加 8Kg 的静负荷力推和拉各10秒钟 轴向虚位间隙0. 4以内
Push-pull (产品焊锡固定在PCB上。) Shaft play in axial
strength of Push and pull static load of 8Kg shall be direction 0.4 Max
shaft applied to the shaft in the axial direction for
10s. (After soldering of the PC board)
6-5. 端子强度 在端子的先端施加5N(500g)的力1分钟。 端子无损坏, 无过度的松动. 允许变形.
Terminal A static load of 5N(500g)be applied to the tip of Without damage or excessive
strength terminals for 1 minute in any direction. looseness of terminals. terminal
bend is permitted.
6-6. 轴套螺纹紧固强度 7. 0kgf. cm以上
Bushing Nut 7. Okgf. cm Min
Tighten Strength
6-7. 轴向间隙 0. 4mm 以下
Shaft play in axial 0.4mm Max
direction
在距离轴顶端5MM处,沿径向瞬间施加50mN.m(500gf.cm)的 0.7*L/30mm p-p 以下(L: 指
6-8. 轴摆动 力测试 安装平面到轴的柄端的距离.)
Shaft wobble A momentary load of 500gf.cm should be applied at the 0.7*L/30mm p-p Max
point 5mm from the tip of the shaft in a direction L:Distance between mounting surfa
perpendicular to the axis of shaft. and measuring point on the shaft
6-9. 轴的回转方向摆动 用角度板测定. 5°以下
Shaft play Testing by angle board. 5° Max
in rotational
wobble

EC11正向系列规格书 EC11 FORWARD DIRECTION SERIES SPECIFICATION

7. 耐久性能 Endurance Characteristics					
项目	条件	规格			
ITEM	CONDITIONS	SPECIFICATIONS			
7-1.回转寿命 Rotational life	在无负荷条件下轴以600~1000周/小时速度回转,一日连续5000~8000次. The shaft of encoder shall be rotated at a speed of 600~1000cycles/H without electrical load, after with measurements shall be made. (5000 to 8000 continuous cycles for 24 hours.)	■在力矩≤100gf.cm时30,000±200周30,000±200cycles per below 100gf.cm.□在力矩>100gf.cm时15,000±200周.15,000±200cycles per above 100gf.cm.振荡 t1,t3≤5mS.突跳 t2≤3mS.尚余有轻微定位感.端子间接触阻抗200Ω以下Chattiring t1,t3≤5mS.Bounce t2≤3mS.Detent feeling has to remains			
7-2.耐湿性 Damp heat	温度40±2℃,湿度90~95%的恒温恒湿槽中放置240±4 小时后,在常温、常湿中放置1.5小时后测试. The encoder shall be stored at temperature of40 ±2℃ with relative humidity of 90% to95% for240±4H in a thermostatic chamber. And the encoder shall be subjected to standard atmospheric conditions for 1.5H, After which measurements shall be made.	Contact resistance 200ΩMax 所有项应满足初期规格 Specifications in clause all items is shall be satisfied.			
7-3.耐热性 Dry heat	温度85±3℃的恒温箱中放置240±4小时, 常温、常湿放置1.5小时后测试. The encoder shall be stored at a temperature of 85±3℃for 240±4H in a thermostatic chamber. And then the encoder. shall be subjected to standard atmospheric conditions for 1.5H, After which measurements shall be made.	所有项应满足初期规格。 Specifications in clause all items is shall be satisfied.			
7-4. 低温特性 Co1d	温度-40±3℃的恒温箱中放置240±4小时, 常温、常湿放置1.5小时后测试. The encoder shall be stored at a temperature of -40±3℃for 240±4H in a thermostatic chamber. And then the encoder. shall be subjected to standard atmospheric conditions for 1.5H, After which	所有项应满足初期规格。 Specifications in clause all items is shall be satisfied.			
7-5. 焊锡耐热性 Resistance to Soldering heat	槽焊 Dip soldering. 使用基板:t=1.6mm的单面覆铜板. Printed wiring board:single-sided copper clad laminate board with thickness of 1.6mm. 预热:基板表面温度100℃以下,时间1分钟以内. Preheating:1.Surface temperature of board:100℃. or less 2.Preheating time:within 1 minute. 焊接:温度260±5℃或以下,时间3秒以内. Soldering:Solder temperature:260±5℃ or less Immersion time:within 3S 手焊 Manual soldering. 温度300℃以下,时间3秒以内. Bit temperature of soldering iron:300℃less than Application time of soldering iron:within 3S	不得有绝缘体的破损、变形、接触无异常. Electrical characteristics shall be satisfied No mechanical abnormality.			
7-6. 焊锡性 Solderability	端子在260℃±5℃温度的焊锡槽内浸锡3秒±0.5秒. The terminals shall be immersed into solder bath at 260℃for 3S±0.5S.	浸渍面须有75%以上焊锡附着 A new uniform coating of solder shall cover75% minimum of the surface being immersed.			

4/5

EC11 FORWARD DIRECTION SERIES SPECIFICATION 推动开关部分Push Switch Portion 口无(NO) ■有(YES) 备注: 以下规格适用于EC11编码器带开关系列. Note: The following specification is only suitable for the one type with switch construction of RE11 encoder series. 1. 额定值 Rating 1-1. 额定电压 Rated voltage:DC 5V 1-2. 最大额定电流(阻抗负载) Maximum operating current (resistive load):10mA Max 2. 电气性能 Electrical Characteristics 项目 条件 规格 ITEM CONDITIONS SPECIFICATIONS 2-1. 接触电阻 用DC 5V 1mA 电压测定. $\leq 100 \text{m} \Omega$ Contact Voltage test at DC 5V 1mA. 100mΩor less resistance 2-2. 绝缘阻抗 在端子和安装板间施加电压 250V DC. 100MΩ 以上 Insulation Measurement shall be made under the condition which a voltage of 250V DC is applied between $100M\Omega$ Min resistance individual terminals and bushing and plank. 2-3. 振荡 ≤10mS 以1秒钟1往返(OFF-ON-OFF)按压动作. Bouncing Shaft shall be push at 1 cycles/s(OFF-ON-OFF) 10mS or less 2-4. 耐电压 在端子和安装板间施加AC300V电压1分钟 不得有绝缘破坏 Dielectric A voltage of 300V AC shall be applied for 1 minute Without arcing or breakdown. between individual terminals and bushing and plank. strength 3. 机械性能 Mechanical Characteristics 3-1. 开关电路 单极单投(按压ON) 接点数 Single pole and single throw Switch circuit and (push ON) number of pulse 3-2. 开关动作力 在轴端,沿轴向施加的按压力. Push static load to the shaft in the axial Operation $500 \pm 200 gf$ fore of switch direction $\blacksquare 0.5 \pm 0.3 \text{ mm}$ 3-3. 开关移动量 $\Box 1.5 \pm 0.5 \text{ mm}$ Travel of switch 4. 耐久性能 Endurance Characteristics 在无负荷条件下沿轴向施以1Kgf以下的力,以600次/小时 ■30,000±200次. (0.5行程) $30,000 \pm 200 \text{ cycles.}$ (0.5 Travel) 的速度按压。 □20,000±200次.(1.5行程) Push 1Kgf to the shaft of encoder in the axial 4-1. 按压寿命 direction under non-load conditions, and with a speed 20,000 ± 200 cycles. (1.5 Travel) 接触电阻:≤200mΩ.其它应满足初期规格. Push-life of 600 times/hour. Contact resistance: $200m\Omega$ or less. Specification in clause shall be satisfied. 受控编号 Document No 修订 Revision 日期 Date 经 办 Designed 审 核 Check 批 准 Approved 初始发行 2020-10-15 文号 File No EC11带定位正向专用

版本 VERSION: